

# Generative models: Support slides.

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# Learning V1

$$p_{\mathcal{D}} = \frac{1}{2}\mathcal{N}(-1, 1) + \frac{1}{2}\mathcal{N}(1, 1), \quad p_{\theta} = \mathcal{N}(\mu, \sigma^2)$$

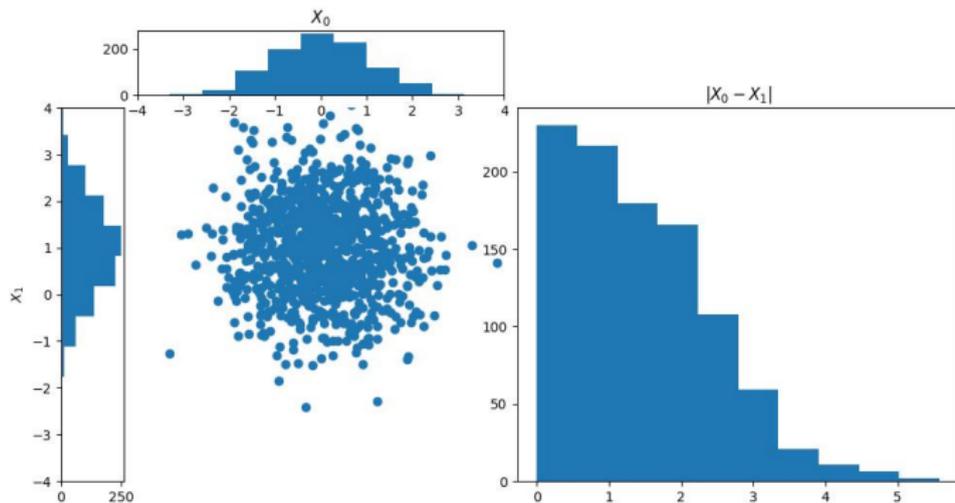
$$\theta \in \arg \min \sum_{i=1}^n \log p_{\theta}(X_i), \quad X_i \sim p_{\mathcal{D}} .$$

## Learning V2

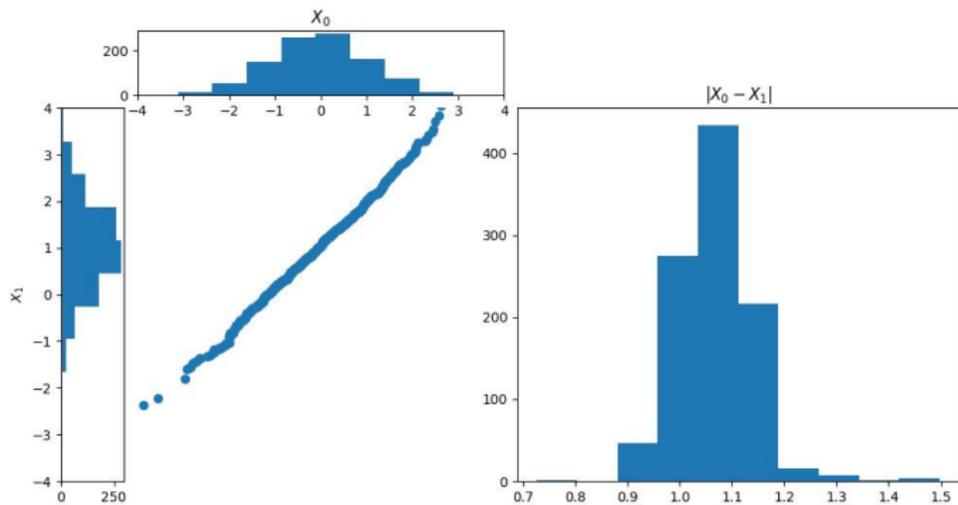
$$p_{\mathcal{D}} = \frac{1}{2}\mathcal{N}(-1, 1) + \frac{1}{2}\mathcal{N}(1, 1), \quad p_{\theta} = \mathcal{N}(\mu, \sigma^2)$$

$$\theta \in \arg \min \sum_{i=1}^n \log p_{\mathcal{D}}(X_i), \quad X_i \sim p_{\theta} .$$

# Coupling $\mathcal{N}(0, 1)$ , $\mathcal{N}(1, 1)$ : Independent



# Coupling $\mathcal{N}(0, 1)$ , $\mathcal{N}(1, 1)$ : Earth Mover distance



# Deep Gauss VAE: Loss

Deep Gauss framework:

- $p_\theta(x|z) = \mathcal{N}(x; \mu_\theta(z), \text{Diag}(\exp(\ln \sigma_\theta^2(z))))$ ,
- $q_\phi(z|x) = \mathcal{N}(z; \mu_\phi(x), \text{Diag}(\exp(\ln \sigma_\phi^2(x))))$ ,

where the neural networks are such that  $\mu_\theta, \ln \sigma_\theta^2 : \mathbb{R}^{d_z} \rightarrow \mathbb{R}^{d_x}$  and  $\mu_\phi, \ln \sigma_\phi^2 : \mathbb{R}^{d_x} \rightarrow \mathbb{R}^{d_z}$ .

$$\begin{aligned} L_{\text{ELBO}}^{mc}(\theta, \phi, x) &= n_{mc}^{-1} \sum_{i=1}^{n_{mc}} -\log p_\theta(x | \mu_\phi(x) + \text{Diag}(\exp(\ln \sigma_\phi^2(x))) Z_i) \\ &\quad + D_{\text{KL}}(q_\phi(\cdot|x) || \mathcal{N}(0, \mathbf{I})) \end{aligned}$$

with  $Z_i \sim \mathcal{N}(0, \mathbf{I})$ . And

$$(\theta_n^*, \phi_n^*) \in \arg \min_{\theta, \phi} n^{-1} \sum_{i=0}^n L_{\text{ELBO}}^{mc}(\theta, \phi, X_i)$$

# Naive Deep Gauss VAE simulation

- $Z_i \sim \mathcal{N}(0, \mathbf{I})$ ,
- $X_i^\theta \sim p_\theta(\cdot | Z_i)$ .

## Score and Denoising: [Vin11, 2011]

If  $X_0 \sim p_{\mathcal{D}}$  and  $X_\sigma = X_0 + \sigma Z$  where  $Z \sim \mathcal{N}(0, \mathbf{I})$  and  $Z \perp\!\!\!\perp X_0$

$$\sigma^2 \nabla \log p_\sigma(x) + x = \mathbb{E}[X_0 | X_\sigma = x] , \quad (1)$$

where  $p_\sigma$  is the density of  $X_\sigma$ .

# SDE framework

Forward SDE:

$$dX_t = -\beta_t X_t dt + \sqrt{2\beta_t} dB_t ,$$

# SDE Framework

Backward SDE:

$$d\overleftarrow{X}_t = (\beta_{T-t}X_t + \beta_{T-t}\nabla \log p_{T-t}(\overleftarrow{X}_t))dt + \sqrt{2\beta_{T-t}}d\tilde{B}_t$$

# Denosing Loss

Denoisier network

$$D_\theta : \mathbb{R}^{d_x} \times \mathbb{R}_+ \ni (x, \sigma) \rightarrow D_\theta(x, \sigma) \in \mathbb{R}^{d_x} \quad (2)$$

Trained on the objective

$$L_{\text{denoiser}} = \mathbb{E}_{\sigma \sim \lambda_\sigma} \left[ \frac{\gamma(\sigma)}{\sigma^2} \mathbb{E} \left[ \|X_0 - D_\theta(X_0 + \sigma Z, \sigma)\|^2 \right] \right], \quad (3)$$

where  $\lambda_\sigma$  is an importance distribution (typically  $\log \mathcal{N}(-1, 1)$ ) and  $\gamma(\sigma)$  a weighting function (typically  $\gamma(\sigma) = 1$ ) which can be tuned on the dataset.

# Score-based sampling

Parameters:  $T, h$ .  $K = T/h$

- Initialization:  $\overleftarrow{X}_0 \sim \mathcal{N}(0, I)$ .
- Inner loop: For  $k \in \{1, \dots, K\}$ :
  - Draw  $Z_k \sim \mathcal{N}(0, I)$
  - Set  $\overleftarrow{X}_{kh} = \beta_{T-(k-1)h}(\overleftarrow{X}_{(k-1)h} + \nabla \log p_{T-t}(\overleftarrow{X}_{(k-1)h}))h + \sqrt{2h\beta_{T-(k-1)h}}Z_k$

## References: Basic theoretical tools

- Basic functional analysis: [Rud87, 1987]
- High dimensional probability: [Ver18, 2018]
- Stochastic processes: [LS01, 2001]
- Information theory: [CT06, 2006]
- Optimal transport: [Vil21, 2021]

## References: Normalizing flows

- Original paper: [RM15, 2015]
- RealNVP: [DSB17, 2017]
- Other famous Flow (Glow) [KD18, 2018]
- Cool application [Sam+22, 2022]

# VAE

- Original paper: [KW13, 2013]
- Tutorial: [KW+19, 2019]
- Theoretical analysis (estimation error): [TY21, 2021]

## Score-based generative models

- Paper that laid out modern foundations: [Son+21b, 2021]
- Paper about training models: [Kar+22, 2022; Kar+24, 2024]
- Theoretical analysis: [Son+21a, 2021; CDS24, 2024]
- Surprising properties of SBGM: [Kad+23, 2023; Zha+24, 2024]

# GANs

- Original paper: [Goo+14, 2014]
- Modern way: [ACB17, 2017]
- Training architectures [Kar+20, 2020]

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